Title of the Paper

First Author*a*, Second Author*b*, Third Author*a,b,[[1]](#footnote-1)*

a*First affiliation, Address, City, Postal code, Country*

b*Second affiliation, Address, City, Postal code, Country*

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Abstract

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, (1)

where *KP* is the proportional gain of the PID control law; *TI* is the reset time; *TD* is the differentiation time; *s* is the Laplace transform variable.

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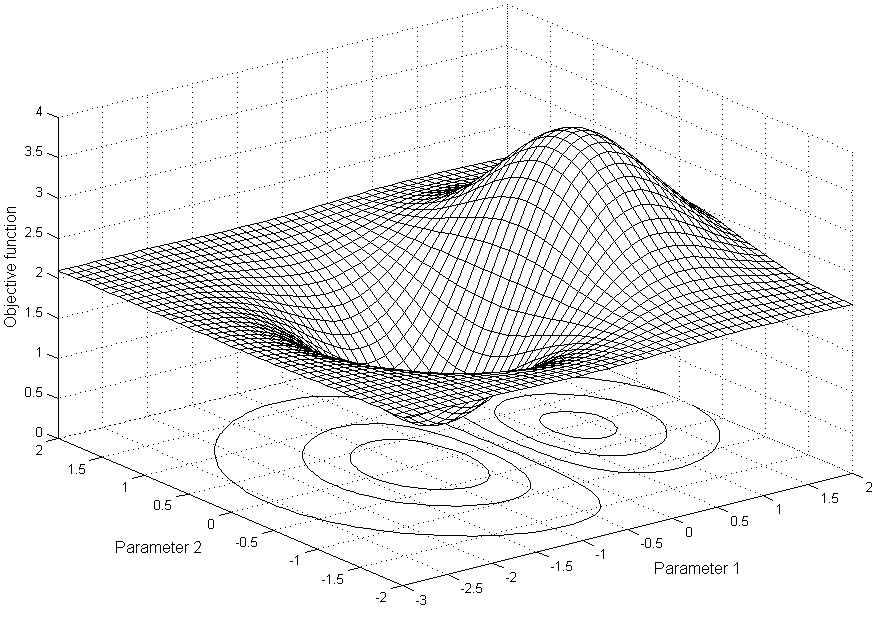


Fig.1. Objective function versus parameter 1 and parameter 2.

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# References

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1. Pistun, Y. , Lesovoy, L. , Matiko, F., Fedoryshyn, R. (2014) Computer Aided Design of Differential Pressure Flow Meters. *World Journal of Engineering and Technology*, **2**, 68-77. doi: [10.4236/wjet.2014.22009](http://dx.doi.org/10.4236/wjet.2014.22009).
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8. R. Fedoryshyn, Y. Hren, F. Matiko. (2009) Modeling of dynamic characteristics of impulse lines of the differential pressure flow meters, *Bulletin of Lviv Polytechnic National University: Heat Power Engineering. Environmental Engineering. Automation*, No. 659, pp. 73-78. (in Ukrainian)

Назва статті

Перший Співавтор*a*, Другий Співавтор*b*, Третій Співавтор*a,b*

a*Перша організація, Адреса, Місто, Поштовий індекс, Країна*

b*Друга організація, Адреса, Місто, Поштовий індекс, Країна*

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**Ключові слова:** від 4 до 8 слів; відділяти крапкою з комою.

1. Corresponding author. Email address: name@mail.com [↑](#footnote-ref-1)